

# **User's Manual**

# **Mobile Phone Power Management Evaluation Board**

APPEB1010 rev.1, Nov., 2006





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# **Mobile Phone Power Management Evaluation Board**

#### Introduction

CAP-XX supercapacitors are thin enough to fit inside a mobile phone and can supply the phone's peak power needs. This evaluation board allows the user to test the CAP-XX power management architecture. Typical peak power loads that need support are the camera phone high brightness LED flash (4x LEDS @ 1A each), the GPRS Power Amplifier and class D audio amplifiers. Depending on the power budget (determined by the on-board adjustable battery current limit) these loads may be supported simultaneously. The board also has connections for other peak power loads that the user may wish to evaluate such as hard drives etc.

Timing circuitry is included for the LED flash (67ms or 133ms) and for the GPRS Power Amplifier simulator (25% duty cycle for class 10 and 2% for network poll simulation). User timing can be connected however take **NOTE** not to exceed the thermal limits of the high brightness LEDs. They should not be turned on for longer than 200ms and allow a rest time of 3s.

#### **Board Summary** (7 sub-circuits)

1.	POWER-	Buck/boost from battery to supercapacitor (3.8V or 5.2V rail). GPRS PA regulator (3.5V), analog (3.3V), reference (1.2V). Adjustable battery current limit upto 2A.
2.	FLASH-	Four high brightness LEDs. Adjustable current limit upto 4A. External LEDs can be connected.
3.	GPRS-	Adjustable PA current upto 2A. External rail can be connected.
4.	TIMING-	PIC microcontroller (space for second controller). On-board or external timing for Flash and GPRS.
5.	AUDIO-	4x 2.75W peak power class D audio amplifiers. Single ended or differential input.
6.	INTERNAL-	DIP switch selectable continuous load simulators.

7. EXTERNAL- Can connect other high power loads.



# **Block Diagram**



#### **Power Load Combinations**

More than one power load is possible at any one time depending on the power budget. The input power available depends on the battery voltage and its allowed current. The evaluation board has an adjustable input current limit (potentiometer R23), which was set to 1.5A for the following examples. The loaded battery voltage was at 3.5V. This gave an average available input power of 5.25W. This section looks at some typical load combinations.



## Network Poll (2% duty cycle) & LED Flash (4A @ 133ms)

This shows that the supercapacitor can provide the 4A required to drive four high brightness LEDs whilst remain in contact with the network (another 1.8A). There is no need to gate the Flash off during network polls eliminating the possibility of dark lines in the photo. Sourcing these 5.8A pulses at an average of approximately 4.5V is impossible without the use of a supercapacitor.



**Network Poll & LED Flash** 



GPRS class 10 & 2W Continuous Audio (1kHz test signal)

In this particular example it can be seen that the PA can be fully supported at 33dBm (1.8A & 3.5V) whilst still providing 2W continuous audio ( $2x4\Omega$  speakers each with 500mA rms). Note that much higher peak power would be available for burst loads (rather than continuous) such as bass (so long as the average does not exceed 2W). There is no need to gate the audio off during class 10 transmissions.





#### Network Poll (2% duty cycle) & 3.3W Continuous Audio

Since the average power for the PA has dropped by a factor of 12.5 (from 25% duty cycle to 2%) more power is available for the audio. In this example the continuous audio power is 3.3W ( $2x4\Omega$  speakers each with 640mA rms). Note that much higher peak power would be available for burst loads (rather than continuous) such as bass (so long as the average does not exceed 3.3W). There is no need to gate the audio off during network polls.





# Circuit Description (refer to schematics at the end of this manual)

#### POWER

- 1. Connect a Li ion battery (or bench top supply) to J3 observing correct polarity (Bat- & Bat+ marked). The Linear Technology buck/boost LTC3442 (U2) has a maximum input voltage of 5.5V and a minimum of 2.4V.
- 2. The current from the battery can be limited up to 2A by adjusting the potentiometer R23. A high current limit enables the maximum power to be delivered to a combination of power loads. A low current limit might only enable one power load however it maximises the battery runtime.
- 3. Jumpers J1 and J2 allow the inductor and supercapacitor current to be measured respectively.
- 4. If the Flash or high power audio is not required then the supercapacitor voltage (output of the buck/boost) may be set to only 3.8V (else 5.2V is required). This is done manually using the toggle switch SW2. This Vout\_select signal is also connected to J8 if remote switching is required.
- 5. J4 and J5 of the EXTERNAL section provide convenient points to measure the supercapacitor voltage.
- 6. Two indicating LEDs are provided to show the input voltage (Vin) and the supercapacitor voltage (Vout). Note that the Vout LED can still be illuminated even when the battery is removed. This is because of the energy stored in the supercapacitor. The LEDs can be disconnected using J7 if their constant drain on the battery is undesirable.

## FLASH

- 1. The LEDs' total current can be measured and adjusted by using a loop on J16 and the potentiometer R34 respectively.
- 2. External LEDs can be tested by connecting them to J16 and J15.
- 3. **DO NOT** use an external timing source that drives the LEDs for longer than 200ms and be sure to allow a 3s thermal recovery time.

#### GPRS

- 1. This simulates a typical GPRS Power Amplifier (PA). The onboard timing is programmed for class 10 (25% duty cycle) or a network poll (2% duty cycle). The current can be measured and adjusted using a loop on J9 and the potentiometer R48 (upto 2A) respectively.
- 2. This board is designed for class 10 operation, if any other timings or rails are connected be sure not to violate the thermal limits of the three power resistors R37,R38,R39 and the MOSFET M2 (Zetex ZXM64N02X).



#### TIMING

- 1. The onboard timing can be used to signal the FLASH and GPRS sections. The preprogrammed timing modes used can be manually chosen by the DIP switch SW4 or they can be remotely chosen using J10.
- 2. The user can implement their own timing modes by connecting directly to J8.
- 3. To use the FLASH with on board timing connect jumpers across pins 5&6, pins 7&8 of J10. This instructs the PIC controller (U7) on the FLASH options of *off* or *on* and *67ms* or *133ms* respectively. Also needed is a jumper across pins 9&10 of J8 to connect this timing signal to the FLASH section.
- 4. The push button switch SW3 can be used instead of pin1 of SW4 for generating the FLASH signal. Holding down this button continuously causes the FLASH to pulse every three seconds.
- 5. To use the GPRS with on board timing connect jumpers across pins 9&10, pins 11&12 of J10. This instructs the PIC controller (U7) on the GPRS options of 2% or 25% and off or on respectively. Also needed is a jumper across pins 13&14 of J8 to connect this timing signal to the GPRS section.

## AUDIO

- 1. There are four separate audio channels each rated at 2.75W (Texas Instruments TPA2032D1). They are designed to drive  $4\Omega$  speakers.
- For single ended input signals, ground the IN+ pin using a jumper on pins 5&7 of the relevant channel jumper (J13, J14, J12, J11). Connect the ground of the input signal to IN+ and the single ended input to IN-. For more information refer to the TPA2032D1 data sheet.

## INTERNAL

 This simulates continuous loads by manually switching in resistors to either the Vout rail (5.2V) or the PA rail (3.5V). Only those resistors connected to the PA rail are presently populated (R5,R4,R3,R1). These resistors are 360Ω, 180Ω, 180Ω, 180Ω respectively. This allows various combinations (using the DIP switch SW1) of 10mA and 20mA.

## EXTERNAL

1. Other high power loads may be connected to this board using J4 & J5 for Vout and J6 & J5 for PA. These jumpers also provide convenient points for measuring the supercapacitor voltage.

## **Further Information**

CAP-XX will be pleased to provide further information on the applications described here, and on the use of supercapacitors in any application. Please use the contact details on the header page, or visit the CAP-XX web site.











